CONTENTS

Konstantin Amelin and Vladislav Ershov Data transfer in a decentralized network of robots using a local voting protocol	219
Konstantin Amelin and Vladimir Maltsev Using of the SPSA method to improve the accuracy of the UAV following a given route under the action of wind loads	
Aleksandr Andreev and Olga Peregudova On global trajectory tracking control of robot manipulators with a delayed feedback	231
Eugenie L. Eremin, Larisa V. Nikiforova, and Evgeniy A. Shelenok Nonlinear repetitive control of the metal cutting machine feed module with saturated input	240
Aliya Imangazieva Investigation of robust ship course control based on auxiliary loop method	248
Sergei Plotnikov Synchronization conditions in networks of Hindmarsh-Rose systems	253
Sergey M. Polozov and Vladimir I. Rashchikov Simulation studies of beam dynamics in 50 MeV linear accelerator with laser-plasma electron gun	260
Evgeniia Sevasteeva, Sergei Plotnikov, and Volodymyr Lynnyk Processing and model design of the gamma oscillation activity based on FitzHugh-Nagumo model and its interaction with slow rhythms in the brain	
Lyubov Shagalova A viscosity solution of the Hamilton–Jacobi equation with exponential dependence of Hamiltonian on the momentum	
Olga Tomchina Control of vibrational field in an elastic vibration unit with DC motors and time-varying observer	277