

TWO PARAMETRIC QUASI-CYCLIC CODES AS HYPERINVARIANT SUBSPACES

M. Isabel García-Planas

Dept. de Matemàtica Aplicada I
Universitat Politècnica de Catalunya
Spain
maria.isabel.garcia@upc.edu

M. Dolors Magret

Dept. de Matemàtica Aplicada I
Universitat Politècnica de Catalunya
Spain
m.dolors.magret@upc.edu

M. Eulalia Montoro

Dept. d'Àlgebra i Geometria
Universitat de Barcelona
Spain
maria.eulalia.montoro@upc.edu

Abstract

It is known the relationship between cyclic codes and invariant subspaces. In this work we present a generalization considering “generalized” cyclic codes and hyperinvariant subspaces.

Key words

Cyclic codes, two-parametric quasi cyclic codes, hyperinvariant subspaces.

1 Introduction

Let φ be an endomorphism of a vector space V over a field \mathbb{F} .

Recall that a φ -invariant subspace $F \subset V$ is called hyperinvariant if F is invariant under all linear maps commuting with φ .

The main goal of this work is to establish the relationship between the set of some “generalized cyclic codes” and hyperinvariant linear subspaces of \mathbb{F}^n .

Despite of the fact that Commutative Algebra is the tool mostly used to study linear cyclic codes (see [MacWilliams and Sloane, 1977], for example), since linear codes have a structure of linear subspaces of \mathbb{F}^n , they can also be studied using Linear Algebra as [Garcia-Planas, Souidi and Um, 2012; Garcia-Planas, Souidi and Um, 2013].

2 Preliminaries

2.1 Hyperinvariant Subspaces of Cyclic Permutation Maps

Let p be a prime number, $q = p^k$ for some $k \geq 1$ and $\mathbb{F} = GF(q)$. Let \mathbb{F}^n be the n -dimensional vector space over the field \mathbb{F} .

We consider the following linear map

$$\begin{aligned} \varphi : \mathbb{F}^n &\longrightarrow \mathbb{F}^n \\ (x_1, \dots, x_n) &\longrightarrow (x_n, x_1, \dots, x_{n-1}) \end{aligned} \quad (1)$$

with associated matrix, with respect to the standard basis,

$$A = \begin{pmatrix} 0 & 0 & \dots & 0 & 1 \\ 1 & 0 & \dots & 0 & 0 \\ 0 & 1 & \dots & 0 & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \dots & 1 & 0 \end{pmatrix}. \quad (2)$$

This linear map is clearly orthogonal (in the sense $A^t = A^{-1}$) and verifies $A^n = I_n$. Cayley Hamilton Theorem ensures that its characteristic polynomial is

$$p(s) = \det(A - sI_n) = (-1)^n (s^n - 1).$$

To study hyperinvariant subspaces (those which are invariant for all linear maps commuting with φ) we need to compute the centralizer of A .

Proposition 2.1. *The centralizer $\mathcal{C}(A)$ of A is the set of circulant matrices*

$$X = \begin{pmatrix} x_1 & x_2 & \dots & x_{n-1} & x_n \\ x_n & x_1 & \dots & x_{n-2} & x_{n-1} \\ x_{n-1} & x_n & \dots & x_{n-3} & x_{n-2} \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ x_2 & x_3 & \dots & x_n & x_1 \end{pmatrix}$$

Proof. It suffices to solve the matrix equation $AX - XA = 0$.

Remark 2.1. *Two matrices belonging to a given centralizer do not necessarily commute. But in our case, given any circulant matrix X commuting with A , its centralizer is $\mathcal{C}(X) = \mathcal{C}(A)$.*

Definition 2.1. Two vectors $x = (x_1, \dots, x_n)$ and $y = (y_1, \dots, y_n)$ in \mathbb{F}^n are called orthogonal when $x \cdot y^t = 0$.

Lemma 2.1.

$$X \in \mathcal{C}(A)$$

if, and only if,

$$X^t \in \mathcal{C}(A)$$

Proof. All circulant matrices satisfy $XX^t = X^tX$ (they are normal matrices) and the Lemma follows.

Proposition 2.2. If F is φ -hyperinvariant subspace, F^\perp is also an hyperinvariant subspace.

Proof. Given any $w \in F^\perp$, $v \in F$, $X \in \mathcal{C}(A)$, we wish to prove that $Xw^t \in F^\perp$. Since

$$(Xw^t)^t v^t = wX^t v^t$$

and taking into account Lemma 2.1 we have that $X^t v^t \in F$ and therefore:

$$wX^t v^t = 0$$

We conclude that $Xw^t \in F^\perp$ and F^\perp is hyperinvariant.

Notice that if $v = (v_1, \dots, v_n)$ is an eigenvector of A , then the following equalities hold:

$$\begin{aligned} v_n &= \lambda v_1 \\ v_1 &= \lambda v_2 \\ &\dots \\ v_{n-2} &= \lambda v_{n-1} \\ v_{n-1} &= \lambda v_n \end{aligned} \tag{3}$$

In particular, we obtain that any eigenvector of A has the form.

$$v = (\lambda^{n-1}, \lambda^{n-2}, \dots, \lambda, 1)$$

We can derive the following Proposition.

Proposition 2.3. Given any $\lambda \in GF(q)^*$ such that $\lambda^n = 1$, then $[v] = [\lambda^{n-1}, \lambda^{n-2}, \dots, \lambda, 1]$, the vector subspace spanned by v , is an hyperinvariant subspace of φ .

Corollary 2.1. The subspace $F = [(1, 1, \dots, 1, 1)]$ is hyperinvariant.

Euler-Fermat Theorem provides information about the roots of $\lambda^n - 1$.

Theorem 2.1. If $\mathbb{F} = GF(q)$, then $\lambda^{q-1} = 1$ has $q-1$ different roots.

Example 2.1. Consider $\mathbb{F} = GF(7)$ and $n = 6$. The characteristic polynomial of A has, in this particular set-up, six different roots. In particular, the eigenvalues of A are $\lambda_1 = 1, \lambda_2 = 2, \lambda_3 = 3, \lambda_4 = 4, \lambda_5 = 5, \lambda_6 = 6$.

In general, we have the following result.

Proposition 2.4. Let v be an eigenvector of A corresponding to the simple eigenvalue α . Then v is an eigenvector of X for all $X \in \mathcal{C}(A)$.

Proof. As a consequence of the definitions,

$$AXv = XAv = X\alpha v = \alpha Xv,$$

then Xv is the zero vector or it is an eigenvector of A of eigenvalue α for all $X \in \mathcal{C}(A)$.

Taking into account that α is a simple root of the characteristic polynomial of a , we have that $Xv = \lambda v$, and the proof is completed.

We can compute the value of the eigenvalue associated to v as follows.

Let v be an eigenvector of A corresponding to the eigenvalue α . Taking into account that $v \neq 0$ we can consider $v = (v_1, \dots, v_{i-1}, 1, v_{i+1}, \dots, v_n)$.

$$\begin{pmatrix} x_1 & x_2 & \dots & x_{n-1} & x_n \\ x_n & x_1 & \dots & x_{n-2} & x_{n-1} \\ x_{n-1} & x_n & \dots & x_{n-3} & x_{n-2} \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ x_2 & x_3 & \dots & x_n & x_1 \end{pmatrix} \begin{pmatrix} v_1 \\ \vdots \\ 1 \\ \vdots \\ v_n \end{pmatrix} = \lambda \begin{pmatrix} v_1 \\ \vdots \\ 1 \\ \vdots \\ v_n \end{pmatrix}$$

Then λ is equal to the i -th coordinate of Xv , $x_{n-i+2}v_1 + \dots + x_{n-i+1}v_n$.

Not only one-dimensional invariant subspaces are hyperinvariant, but all invariant subspaces are also hyperinvariant.

Proposition 2.5. Let F be a φ -invariant subspace. Then F it is hyperinvariant.

Proof. It suffices to observe that, for all $X \in \mathcal{C}(A)$,

$$X = x_1 I + x_2 A^{n-1} + \dots + x_{n-1} A^2 + x_n A.$$

Then F is an invariant subspace of X .

2.2 Linear Cyclic Codes

Let us assume that characteristic of \mathbb{F} does not divide the length of the code n . This assumption is an usual one in the theory of cyclic block-codes in order to guarantee that the polynomial $s^n - 1$ factorize into different prime polynomials over \mathbb{F} .

Definition 2.2. A code C of length n over the field \mathbb{F} is called cyclic if whenever $c = (a_1, \dots, a_n)$ is in C , its cycle shift $sc = (a_n, a_1, \dots, a_{n-1})$ is also in C .

Example 2.2. The linear code $C = \{000, 110, 011, 101\}$ over $GF(2)$ is cyclic. To prove that, we compute the shift sc for all $c \in C$: $s(000) = 000$, $s(110) = 011$, $s(011) = 101$, and $s(101) = 110$.

It is easy to prove the following statement from the Definitions.

Let P_3 be a full cycle permutation matrix obtained from the identity matrix I_3 by moving its first column to the last column (observe that P_3 corresponds to the matrix A of Equation (2) for $n = 3$). The shift sc can be expressed as

$$\begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 & 0 & 1 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 1 \end{pmatrix} = \begin{pmatrix} 0 & 0 & 1 & 1 \\ 0 & 1 & 0 & 1 \\ 0 & 1 & 1 & 0 \end{pmatrix}$$

In general, the shift sc can be expressed as $P_n c^t$ where P_n is a full cycle permutation matrix obtained from the identity matrix I_n by moving its first column to the last column.

Taking into account that P_n is a linear transformation of \mathbb{F}^n (the map φ as defined in Equation (1)), we can construct a cyclic code, as follows. Take a word c , and consider the set S consisting of c and its successive images by P_n :

$$S = \{c^t, P_n c^t, \dots, P_n^{n-1} c^t\}$$

The linear subspace C , defined as the linear space spanned by S , $C = [S]$, is the smallest linear cyclic code containing c .

Next two Propositions are proved in [Radkova and Van-Zanten, 2009] and [Radkova, Bojilov and Van-Zanten, 2007].

Proposition 2.6. A linear code C of length n over the field \mathbb{F} is cyclic if, and only if, C is an A -invariant subspace of \mathbb{F}^n .

Proposition 2.7. Let C be a cyclic code, and $p(s) = (-1)^n p_1(s) \cdot \dots \cdot p_r(s)$ the decomposition of $p(s)$ in prime factors. Then $C = \text{Ker } p_{i_1}(A) \oplus \dots \oplus \text{Ker } p_{i_s}(A)$ for some minimal φ -invariant subspaces $\text{Ker } p_{i_j}(A)$ of \mathbb{F}^n .

After Proposition 2.5 we deduce the following result.

Proposition 2.8. A linear code C with length n over the field \mathbb{F} is cyclic if, and only if, C is an A -hyperinvariant subspace of \mathbb{F}^n .

Example 2.3. Consider the matrix A of φ for $n = 7$ and $q = 2$. Then we have $p(s) = s^7 + 1$. Factorizing $p(s)$ into prime factors over $GF(2)$ we have that $p(s) = p_1(s)p_2(s)p_3(s) = (s + 1)(s^3 + s + 1)(s^3 + s^2 + 1)$. The factors $p_i(s)$ define minimal P_n -invariant subspaces $F_i = \text{Ker } p_i(A)$, for $i = 1, 2, 3$.

We define a cyclic linear code C by

$$C = F_1 \oplus F_2 = \text{Ker}(p_1(A)) \oplus \text{Ker}(p_2(A))$$

$p_1(s) \cdot p_2(s) = s^4 + s^3 + s^2 + 1$ and $A^4 + A^3 + A^2 + I$ is the following matrix

$$\begin{pmatrix} 1 & 0 & 0 & 1 & 1 & 1 & 0 \\ 0 & 1 & 0 & 0 & 1 & 1 & 1 \\ 1 & 0 & 1 & 0 & 0 & 1 & 1 \\ 1 & 1 & 0 & 1 & 0 & 0 & 1 \\ 1 & 1 & 1 & 0 & 1 & 0 & 0 \\ 0 & 1 & 1 & 1 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 & 1 & 0 & 1 \end{pmatrix}$$

$$\text{Ker}(A^4 + A^3 + A^2 + I) = [(1, 0, 1, 1, 0, 0, 0), (1, 1, 1, 0, 0, 1, 0, 0), (1, 1, 0, 0, 0, 0, 1, 0), (0, 1, 1, 0, 0, 0, 0, 1)]$$

3 Generalized Case

If $q > 2$, we can generalize the above case as follows.

$$\begin{aligned} \varphi_{a,b,c} : \mathbb{F}^n &\longrightarrow \mathbb{F}^n \\ (x_1, \dots, x_n) &\longrightarrow (a \cdot x_n, b \cdot x_1, c \cdot x_2, \dots, c \cdot x_{n-1}) \end{aligned}$$

with associated matrix with respect to the standard basis,

$$A_{a,b,c} = \begin{pmatrix} 0 & 0 & \dots & 0 & a \\ b & 0 & \dots & 0 & 0 \\ 0 & c & \dots & 0 & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \dots & c & 0 \end{pmatrix}$$

for a, b, c such that $abc \neq 0$.

The characteristic polynomial of $A_{a,b,c}$ is $p_{a,b,c}(s) = (-1)^n (s^n - c^{n-2}ab)$,

Proposition 3.1. The centralizer $\mathcal{C}(A_{a,b,c})$ of $A_{a,b,c}$ is

the set of matrices $X_{a,b,c}$ with:

$$X_{a,b,c} = \begin{pmatrix} x_n & \frac{a}{b}x_1 & \frac{a}{c}x_2 & \frac{a}{c^2}x_3 & \dots & \frac{a}{c^{n-2}}x_{n-2} & \frac{a}{c}x_{n-1} \\ \frac{b}{c}x_{n-1} & x_n & \frac{a}{c}x_1 & \frac{ab}{c^2}x_2 & \dots & \frac{ab}{c^2}x_{n-3} & \frac{ab}{c^2}x_{n-2} \\ \vdots & & \ddots & \ddots & & & \\ \vdots & & & \ddots & \ddots & & \\ \frac{b}{c}x_3 & x_4 & x_5 & x_6 & \dots & \frac{a}{c}x_1 & \frac{ab}{c^2}x_2 \\ \frac{b}{c}x_2 & x_3 & x_4 & x_5 & \dots & x_n & \frac{a}{c}x_1 \\ x_1 & x_2 & x_3 & x_4 & \dots & x_{n-1} & x_n \end{pmatrix}$$

Proof. It suffices to solve the matrix equation $A_{a,b,c}X_{a,b,c} - X_{a,b,c}A_{a,b,c} = 0$.

Notice that if $v = (v_1, \dots, v_n)$ is an eigenvector of $A_{a,b,c}$, then:

$$\begin{aligned} av_n &= \lambda v_1 \\ bv_1 &= \lambda v_2 \\ cv_2 &= \lambda v_3 \dots \\ cv_{n-2} &= \lambda v_{n-1} \\ cv_{n-1} &= \lambda v_n \end{aligned} \tag{4}$$

In particular, we obtain that

$$v = (\lambda^{n-1}b^{-1}c^{-(n-2)}, \lambda^{n-2}c^{-(n-2)}, \dots, \lambda c^{-1}, 1)$$

and we have the following Proposition.

Proposition 3.2. Let $\lambda \in GF(q)^*$ be an element such that $\lambda^n = abc^{n-2}$. Then $[v] = [(\lambda^{n-1}b^{-1}c^{-(n-2)}, \lambda^{n-2}c^{-(n-2)}, \dots, \lambda c^{-1}, 1)]$ is an hyperinvariant subspace.

Proof.

$$A_{a,b,c}v = \lambda v$$

and given any $X_{a,b,c} \in \mathcal{C}(A_{a,b,c})$, then

$$\begin{aligned} X_{a,b,c}v &= \\ (x_1I + \frac{x_2}{c}A_{a,b,c} + \frac{x_3}{c^2}A_{a,b,c}^2 + \dots + \\ + \frac{x_{n-1}}{c^{n-2}}A_{a,b,c}^{n-2} + \frac{x_n}{bc^{n-2}}A_{a,b,c}^{n-1})v &= \\ x_1v + \frac{x_2}{c}\lambda v + \frac{x_3}{c^2}\lambda^2v + \dots + \\ + \frac{x_{n-1}}{c^{n-2}}\lambda^{n-2}v + \frac{x_n}{bc^{n-2}}\lambda^{n-1}v &= \\ \alpha v \end{aligned}$$

with $\alpha = x_1 + \frac{x_2}{c}\lambda + \frac{x_3}{c^2}\lambda^2 + \dots + \frac{x_{n-1}}{c^{n-2}}\lambda^{n-2} + \frac{x_n}{bc^{n-2}}\lambda^{n-1} \in \mathbb{F}$.

Proposition 3.3. Let F be an invariant subspace of $A_{a,b,c}$. Then F is hyperinvariant.

Proof. It suffices to observe that, for all $X_{a,b,c} \in \mathcal{C}(A_{a,b,c})$ then

$$X_{a,b,c} = x_1I + \frac{x_2}{c}A_{a,b,c} + \frac{x_3}{c^2}A_{a,b,c}^2 + \dots + \frac{x_{n-1}}{c^{n-2}}A_{a,b,c}^{n-2} + \frac{x_n}{bc^{n-2}}A_{a,b,c}^{n-1}.$$

Therefore, we have that in this case the lattices of invariant and hyperinvariant subspaces are equal, i.e.:

$$Hinv(A_{a,b,c}) = Inv(A_{a,b,c})$$

3.1 Particular Case $b = 1$

Notice that it suffices to solve the case $b = 1$ because:

$$A_{a,b,c}X - XA_{a,b,c} = D(A_{a/b,1,c/b}X - XA_{a/b,1,c/b})$$

with $D = \text{diag}(b)$.

So, we write the results in this simpler case.

Given $a, c \neq 0$, we consider the following linear map:

$$\begin{aligned} \varphi_{a,c} : \mathbb{F}^n &\longrightarrow \mathbb{F}^n \\ (x_1, \dots, x_n) &\longrightarrow (a \cdot x_n, x_1, c \cdot x_2, \dots, c \cdot x_{n-1}) \end{aligned}$$

with associated matrix with respect to the standard basis,

$$A_{a,c} = \begin{pmatrix} 0 & 0 & 0 & \dots & 0 & a \\ 1 & 0 & 0 & \dots & 0 & 0 \\ 0 & c & 0 & \dots & 0 & 0 \\ 0 & 0 & c & \dots & 0 & 0 \\ \vdots & & & \ddots & & \\ 0 & 0 & 0 & \dots & c & 0 \end{pmatrix}$$

The characteristic polynomial of $A_{a,c}$ is

$$p_{a,c}(s) = (-1)^n(s^n - c^{n-2}a),$$

Proposition 3.4. The centralizer $\mathcal{C}(A_{a,c})$ of $A_{a,c}$ is the set of matrices $X_{a,c}$ with:

$$X_{a,c} = \begin{pmatrix} x_n & ax_1 & \frac{a}{c}x_2 & \frac{a}{c^2}x_3 & \dots & \frac{a}{c}x_{n-2} & \frac{a}{c}x_{n-1} \\ \frac{1}{c}x_{n-1} & x_n & \frac{a}{c}x_1 & \frac{a}{c^2}x_2 & \dots & \frac{a}{c^2}x_{n-3} & \frac{a}{c^2}x_{n-2} \\ \vdots & & \ddots & \ddots & & & \\ \vdots & & & \ddots & \ddots & & \\ \frac{1}{c}x_3 & x_4 & x_5 & x_6 & \dots & \frac{a}{c}x_1 & \frac{a}{c^2}x_2 \\ \frac{1}{c}x_2 & x_3 & x_4 & x_5 & \dots & x_n & \frac{a}{c}x_1 \\ x_1 & x_2 & x_3 & x_4 & \dots & x_{n-1} & x_n \end{pmatrix}$$

Proof. It follows from Proposition 3.1, when $b = 1$.

Notice that if $v = (v_1, \dots, v_n)$ is an eigenvector of $A_{a,c}$, then:

$$\begin{aligned} av_n &= \lambda v_1 \\ v_1 &= \lambda v_2 \\ &\dots \\ cv_{n-2} &= \lambda v_{n-1} \\ cv_{n-1} &= \lambda v_n \end{aligned} \tag{5}$$

In particular, we obtain that

$$v = (\lambda^{n-1}c^{-(n-2)}, \lambda^{n-2}c^{-(n-2)}, \dots, \lambda^{-1}, 1)$$

and we have the following Proposition.

Proposition 3.5. *Given any $\lambda \in GF(q)^*$ such that $\lambda^n = ac^{n-2}$, then $v = (\lambda^{n-1}c^{-(n-2)}, \lambda^{n-2}c^{-(n-2)}, \dots, \lambda c^{-1}, 1)$ is an hyperinvariant subspace.*

Proposition 3.6. *Let F be an invariant subspace of $A_{a,c}$. Then it is hyperinvariant.*

Proof. It suffices from Proposition 3.3 that for all $X_{a,c} \in \mathcal{C}(A_{a,c})$ then

$$X_{a,c} = x_1 I + \frac{x_2}{c} A_{a,c} + \frac{x_3}{c^2} A_{a,c}^2 + \dots + \frac{x_{n-1}}{c^{n-2}} A_{a,c}^{n-2} + \frac{x_n}{c^{n-1}} A_{a,c}^{n-1}.$$

3.2 Two-parametric Quasi-Cyclic Codes

In this section, we will to generalize the concept of constacyclic code as follows.

Definition 3.1. *Let a, c be two nonzero elements of \mathbb{F} . A code C with length n over the field \mathbb{F} is called generalized constacyclic code if whenever $c = (a_1, \dots, a_n)$ is in C , so is $sc = (a \cdot a_n, a_1, c \cdot a_2, \dots, c \cdot a_{n-1})$.*

As immediate consequence of definition we have the following Proposition.

Proposition 3.7. *A linear code C with length n over the field \mathbb{F} is generalized constacyclic if, and only if, C is an $A_{a,c}$ -invariant subspace of \mathbb{F}^n .*

After Proposition 3.6 we have the following result.

Proposition 3.8. *A linear code C with length n over the field \mathbb{F} is two-parameter cyclic if, and only if, C is a $A_{a,c}$ -hyperinvariant subspace of \mathbb{F}^n .*

Suppose now that $(n, q) = 1$ and $p_{a,c}(s) = (-1)^n(s^n - c^{n-2}a)$ has no multiple roots and splits into distinct irreducible monic factors.

Proposition 3.9. *Let C be generalized constacyclic code, and $p_{a,c}(s) = (-1)^n p_{a,c_1}(s) \cdot \dots \cdot p_{a,c_r}(s)$ the decomposition of $p_{a,c}(s)$ in irreducible factors. Then $C = \text{Ker } p_{a,c_{i_1}}(A_{a,c}) \oplus \dots \oplus \text{Ker } p_{a,c_{i_s}}(A_{a,c})$ for some minimal $A_{a,c}$ -invariant subspaces $\text{Ker } p_{a,c_{i_j}}(A_{a,c})$ of \mathbb{F}^n .*

Proof. First, it is easy to see that $\text{Ker } p_{a,c_i}(A_{a,c})$ for $i = 1, \dots, r$ are $A_{a,c}$ -invariant: let $v \in \text{Ker } p_{a,c_i}(A_{a,c})$ then $A_{a,c}v = p_{a,c_1}(A_{a,c}) \cdot \dots \cdot p_{a,c_r}(A_{a,c})v = 0$.

The subspaces $\text{Ker } p_{a,c_{i_j}}(A_{a,c})$ are minimal because the polynomials $p_{a,c_{i_j}}(s)$ are irreducible.

Now, we define $\widehat{p}_i(s) = p_{a,c}(s)/p_{a,c_i}(s)$. Taking into account $(\widehat{p}_1(s), \dots, \widehat{p}_r(s)) = 1$, there exist polynomials $q_1(s), \dots, q_r(s)$ such that $q_1(s)\widehat{p}_1(s) + \dots + q_r(s)\widehat{p}_r(s) = 1$.

Let $x \in C$, then $x = q_1(A_{a,c})\widehat{p}_1(A_{a,c})x + \dots + q_r(A_{a,c})\widehat{p}_r(A_{a,c})x$. Calling $x_i = q_i(A_{a,c})\widehat{p}_i(A_{a,c})x$ and taking into account that C is $A_{a,c}$ -invariant, and that $x_i \in \text{Ker } p_{a,c_i}(A_{a,c})$ we have that $x_i \in C \cap \text{Ker } p_{a,c_i}(A_{a,c})$.

Example 3.1. *Consider the matrix $A_{a=2,c=4}$ for $n = 8, q = 5$. Then we have $p(s) = p_{a=2,c=4}(s) = s^8 - 1$. Factorizing $p(s)$ into irreducible factors over $\mathbb{F} = GF(5)$ we have $p(s) = p_1(s)p_2(s)p_3(s)p_4(s)p_5(s)p_6(s) = (s+1)(s+2)(s+3)(s+4)(s^2+2)(s^2+3)$. The factors $p_i(s)$ define minimal $A_{a,c}$ -invariant subspaces $F_i = \text{Ker } p_i(A_{a,c})$, for $i = 1, 2, 3, 4, 5, 6$.*

We define a generalized constacyclic linear code $C_{a,c}$ by

$$C_{a,c} = F_1 \oplus F_5 = \text{Ker}(p_1(A_{a,c})) \oplus \text{Ker}(p_5(A_{a,c}))$$

$p_1(s) \cdot p_5(s) = s^3 + s^2 + 2s + 2$ and $A_{a,c}^3 + A_{a,c}^2 + 2A_{a,c} + 2I$ is the following matrix

$$\begin{pmatrix} 2 & 0 & 0 & 0 & 0 & 1 & 3 & 3 \\ 2 & 2 & 0 & 0 & 0 & 0 & 3 & 4 \\ 2 & 4 & 2 & 0 & 0 & 0 & 0 & 3 \\ 4 & 4 & 4 & 2 & 0 & 0 & 0 & 0 \\ 0 & 3 & 4 & 4 & 2 & 0 & 0 & 0 \\ 0 & 0 & 3 & 4 & 4 & 2 & 0 & 0 \\ 0 & 0 & 0 & 3 & 4 & 4 & 2 & 0 \\ 0 & 0 & 0 & 0 & 3 & 4 & 4 & 2 \end{pmatrix}$$

$$\begin{aligned} \text{Ker}(A_{a,c}^3 + A_{a,c}^2 + 2A_{a,c} + 2I) = \\ [(1, 4, 2, 1, 3, 4, 2, 1), (1, 0, 4, 0, 2, 0, 1, 0), \\ (0, 3, 0, 4, 0, 2, 0, 1)]. \end{aligned}$$

3.3 Particular Case: $b = c = 1$

$$\begin{aligned} \varphi_a : \mathbb{F}^n &\longrightarrow \mathbb{F}^n \\ (x_1, \dots, x_n) &\longrightarrow (a \cdot x_n, x_1, \dots, x_{n-1}) \end{aligned}$$

where $a \neq 0$ and associated matrix respect to the standard basis,

$$A_a = \begin{pmatrix} 0 & 0 & \dots & 0 & a \\ 1 & 0 & \dots & 0 & 0 \\ 0 & 1 & \dots & 0 & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \dots & 1 & 0 \end{pmatrix}.$$

This linear map verifies $A_a^{-1} = A_{1/a}^t$. The characteristic polynomial is

$$p(s) = \det(A_a - sI_n) = (-1)^n (s^n - a).$$

Proposition 3.10. *The centralizer $\mathcal{C}(A_a)$ of A_a is the set of matrices*

$$X_a = \begin{pmatrix} x_1 & ax_2 & \dots & ax_{n-1} & ax_n \\ x_n & x_1 & \dots & ax_{n-2} & ax_{n-1} \\ x_{n-1} & x_n & \dots & ax_{n-3} & ax_{n-2} \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ x_2 & x_3 & \dots & x_n & x_1 \end{pmatrix}$$

Proof. Is a particular case of Proposition 3.1.

Remark 3.1. *If $X_a \in \mathcal{C}(A_a)$ then $X_a^t \in \mathcal{C}(A_{1/a})$. For that, it suffices to observe suffices to observe that*

$$X_a^t = \begin{pmatrix} x_1 & \frac{1}{a}x_n & \dots & \frac{1}{a}x_3 & \frac{1}{a}x_2 \\ x_2 & x_1 & \dots & \frac{1}{a}x_{n-3} & \frac{1}{a}x_{n-2} \\ x_3 & x_2 & \dots & \frac{1}{a}x_{n-3} & \frac{1}{a}x_{n-2} \\ \vdots & \ddots & \vdots & \ddots & \vdots \\ x_n & x_{n-1} & \dots & x_2 & x_1 \end{pmatrix} \in \mathcal{C}(A_{1/a})$$

where $y_1 = x_1$ and $y_i = ax_i$ for all $i \neq 1$.

Proposition 3.11. *Let F be a hyperinvariant subspace of A_a . Then, F^\perp is a hyperinvariant subspace of $A_{1/a}$.*

Proof. Given any $w \in F^\perp$, $c \in F$, $X \in \mathcal{C}(A_a)$, if $(w')^t = X^t w^t$ then, we have:

$$w' c^t = w X c^t = 0$$

and then $X^t w^t = (w')^t \in F^\perp$ and F^\perp is invariant for any matrix in $\mathcal{C}(A_{1/a})$; that is to say, it is an hyperinvariant subspace for $A_{1/a}$.

Notice that if $v = (v_1, \dots, v_n)$ is an eigenvector of A_a , then the following equalities hold:

$$\begin{aligned} av_n &= \lambda v_1 \\ v_1 &= \lambda v_2 \\ &\dots \\ v_{n-2} &= \lambda v_{n-1} \\ v_{n-1} &= \lambda v_n \end{aligned} \tag{6}$$

In particular, we obtain that

$$v = (\lambda^{n-1}, \lambda^{n-2}, \dots, \lambda, 1)$$

and we have the following Proposition.

Proposition 3.12. *Given any $\lambda \in GF(q)^*$ such that $\lambda^n = a$, then $[v] = [(\lambda^{n-1}, \lambda^{n-2}, \dots, \lambda, 1)]$ is an hyperinvariant subspace.*

Proposition 3.13. *Let F be an invariant subspace of A_a . Then it is hyperinvariant.*

Proof. It suffices to observe that, for all $X_a \in \mathcal{C}(A_a)$,

$$X_a = x_1 I + x_2 A_a + \dots + x_{n-1} A_a^{n-2} + x_n A_a^{n-1}.$$

Example 3.2. *Over $\mathbb{F} = GF(5)$ we consider*

$$A_2 = \begin{pmatrix} 0 & 0 & 2 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}$$

$F = [(1, 2, 4)]$ is invariant

$$\begin{pmatrix} 0 & 0 & 2 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 2 \\ 4 \end{pmatrix} = 3 \begin{pmatrix} 1 \\ 2 \\ 4 \end{pmatrix}$$

and also it is hyperinvariant

$$\begin{pmatrix} x_1 & 2x_2 & 2x_3 \\ x_3 & x_1 & 2x_2 \\ x_2 & x_3 & x_1 \end{pmatrix} \begin{pmatrix} 1 \\ 2 \\ 4 \end{pmatrix} = (x_1 + 4x_2 + 3x_3) \begin{pmatrix} 1 \\ 2 \\ 4 \end{pmatrix}.$$

Notice that in fact we have solved the following slightly more general case with $b = c$

$$\begin{aligned} \varphi_{ab} : \mathbb{F}^n &\longrightarrow \mathbb{F}^n \\ (x_1, \dots, x_n) &\longrightarrow (a \cdot x_n, b \cdot x_1, \dots, b \cdot x_{n-1}) \end{aligned}$$

with associated matrix with respect to the standard basis,

$$A_{ab} = \begin{pmatrix} 0 & 0 & \dots & 0 & a \\ b & 0 & \dots & 0 & 0 \\ 0 & b & \dots & 0 & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \dots & b & 0 \end{pmatrix}.$$

for a, b such that $ab \neq 0$ because of

$$A_{a,b} X - X A_{a,b} = D(A_{a/b} X - X A_{a/b})$$

with $D = \text{diag}(b)$.

3.4 Constacyclic Codes

A particular case of generalized constacyclic codes are constacyclic codes which were introduced in [Berlekamp, 1968].

Definition 3.2. Let a be a nonzero element of \mathbb{F} . A code C with length n over the field \mathbb{F} is called constacyclic with respect to a if whenever $c = (a_1, \dots, a_n)$ is in C , so is its cycle constashift $sc = (a \cdot a_n, a_1, \dots, a_{n-1})$.

Obviously, when $a = 1$ the constacyclic code is cyclic.

The constashift sc can be expressed as $P_{a_n}c^t$ where P_{a_n} is a generalized full cycle permutation matrix obtained from the identity matrix I_n by moving its first column multiplied by a to the last column.

$$P_{a_n} = \begin{pmatrix} 0 & 0 & \dots & 0 & a \\ 1 & 0 & & & 0 \\ \vdots & \ddots & & \vdots & \vdots \\ 0 & 0 & \dots & 1 & 0 \end{pmatrix}$$

According to [Radkova and Van-Zanten, 2009], we have the following Propositions.

Proposition 3.14. A linear code C with length n over the field \mathbb{F} is constacyclic if, and only if, C is an P_{a_n} -invariant subspace of \mathbb{F}^n .

Suppose now that $(n, q) = 1$ and $p_a(s) = (-1)^n(s^n - a)$ has no multiple roots and splits into distinct irreducible monic factors.

Proposition 3.15. Let C be a constacyclic code, and $p_a(s) = (-1)^n p_{a_1}(s) \dots p_{a_r}(s)$ the decomposition of $p_a(s)$ in irreducible factors. Then $C = \text{Ker } p_{a_{i_1}}(A) \oplus \dots \oplus \text{Ker } p_{a_{i_s}}(A)$ for some minimal φ_a -invariant subspaces $\text{Ker } p_{a_{i_j}}(A)$ of \mathbb{F}^n .

After Proposition 3.13 we deduce the following result.

Proposition 3.16. A linear code C with length n over the field \mathbb{F} is constacyclic if and only if C is an A_a -hyperinvariant subspace of \mathbb{F}^n .

Example 3.3. Consider the matrix $A_{a=4}$ for $n = 8$, $q = 5$. Then we have $p(s) = s^8 - 4$. Factorizing $p(s)$ into irreducible factors over $GF(5)$ we have $p(s) = p_1(s)p_2(s) = (s^4 - 2)(s^4 + 2)$. The factors $p_i(s)$ define minimal P_{a_n} -invariant subspaces $F_i = \text{Ker } p_i(A_a)$, for $i = 1, 2$.

We define a constacyclic linear code C_a by

$$C_a = F_1 = \text{Ker } (p_1(A))$$

$p_1(s) = s^4 - 2$ and $A^4 - 2I$ is the following matrix

$$\begin{pmatrix} 3 & 0 & 0 & 0 & 4 & 0 & 0 & 0 \\ 0 & 3 & 0 & 0 & 4 & 0 & 0 & 0 \\ 0 & 0 & 3 & 0 & 0 & 4 & 0 & 0 \\ 0 & 0 & 0 & 3 & 0 & 0 & 4 & 0 \\ 1 & 0 & 0 & 0 & 3 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 3 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 & 3 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 3 \end{pmatrix}$$

$$\text{Ker } (A^4 - 2I) = [(2, 0, 0, 0, 1, 0, 0, 0), (0, 2, 0, 0, 0, 1, 0, 0), (0, 0, 2, 0, 0, 0, 1, 0), (0, 0, 0, 2, 0, 0, 0, 1)]$$

References

Astuti, P., and Wimmer, H.K., (2011). *Characteristic and hyperinvariant subspaces over the field GF(2)*. Linear Algebra Appl, doi:10.1016/j.laa.2011.03.047.
 Berlekamp, E.R., (1968). *Algebraic Coding Theory*. Mc Graw-Hill Book Company, New York.
 Garcia-Planas M.I., Soudi El M., and Um L.E., (2012). *Analysis of control properties of concatenated convolutional codes*. Cybernetics and Physics. 1(4), pp. 252–257.
 Garcia-Planas, M.I., Soudi, El M., and Um, L.E., (2013). *Convolutional codes under control theory point of view. Analysis of output-observability*. Recent Advances in Circuits, Communications & Signal Processing, pp. 131–137.
 Gluesing-Luerssen, H., and Schmale, W., (2004) *On Cyclic Convolutional Codes*. Acta Applicandae Mathematicae, 82, pp. 183–237.
 MacWilliams, F.G., and Sloane, N.J.A., (1977). *The Theory of Error Correcting Codes*. North-Holland Publ. Company, Amsterdam.
 Radkova, D., Bojilov, A., and Van Zanten, A.J., (2007). *Cyclic Codes and Quasi-Twisted Codes: an Algebraic Approach*. Report MICC 07-08, Universiteit Maastricht.
 Radkova, D., and Van Zanten, D.J., (2009). *Constacyclic codes as invariant subspaces*. Linear Algebra and its Applications, 430, pp. 855–864.